# **LATCHING SOLENOIDS**

## **Featuring Long-Stroke Specifications**

• 10 mm (ordinarily 5 mm)



#### TSB-LS

(Low-Noise Model)

Suppresses operating noise.

## **High Durability**

- 500,000 cycles
- \* (as tested by Takano Co. in a standard testing environment)

#### **FEATURES**

## Bi-stable Driving Force

Since our models carry out reciprocating motion without the use of springs, operating instead on the change of electrical current, our models maintain a stable response speed with no variation in torque upon activation. Even when current is cut off, the solenoid stays in its position using the holding force of a permanent magnet.

## Power-Saving/Low-Heat

Since current is only required when driving the solenoid, no holding current is required. This makes the device both energy-efficient and free from problems caused by coil temperature rise or heat generation. (This is because the shaft stays in position using the magnetic force of a permanent magnet, even after the coil is deenergized.)

#### **APPLICATIONS**

#### 1. Light Control

can be used to block or polarize light, to switch between lights, and to change the color or amount of light.

#### 2. Sorting/Screening

can be used to sort or screen (mail, etc.).

#### 3. Locking/Positioning

can be used for electric locking or halting (of moving items on a conveyor belt, etc.).

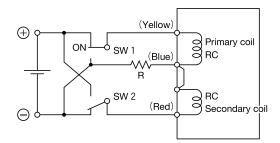
#### 4. Valves

can be used to open and close plumbing or tubing by means of a clamp.

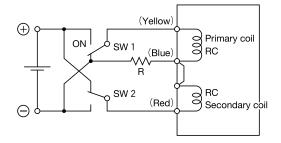
## 1 OPERATING PRINCIPLES

#### TSB Series

When switch SW1 is turned on (with SW2 off), the shaft is pulled to the primary coil side. Even if switch SW1 is reset the shaft stays in position.



When switch SW2 is turned on (with SW1 off), the shaft is pulled to the secondary coil side. Even if switch SW2 is reset the shaft maintains its position.



In either case, in order to cancel out the holding power of the permanent magnet on both coils (not just on the holding side), it is necessary to insert an external resistor (R) for degaussing. Thus, the unit operates on a two-loop structure.

## 2 INSTRUCTIONS AND PRECAUTIONS FOR USE

#### Attractive Force Data

The attractive force data of each of our products were measured by means of a load-testing device in a standard testing environment, with no load and with the shafts in a vertical position. Since we are able to adjust the stroke and attractive force to best match your intended load, please feel free to consult with us.

#### Response Characteristics

The response characteristics of each of our products were measured in a standard testing environment with no load and with the shafts in a horizontal position; we measured the current waveform while the product was stabilized in a heat sink.

Standard Testing Environment · · · · Ambient Temp  $20\pm15\,^\circ$ C, Relative Humidity  $65\pm20\,^\circ$ K, Air Pressure  $860\,^\circ$  1060 hPA

Heat Sink · · · · 80 mm square, 3 mm thick, aluminum

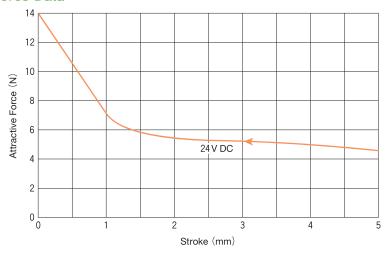
#### Duty Cycle/Temperature Change Over Short Periods of Time/ Coil Saturation Temperature Rise

You can consider these factors as similar to those of our bi-stable rotary solenoids. Please refer to BI-STABLE ROTARY SOLENOIDS INSTRUCTIONS AND PRECAUTIONS FOR USE, pp.6 $\sim$ 7.

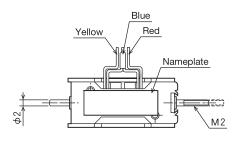
Working Voltage	24 (V DC)
DC Resistance	10 (Ω)
External Resistance	1.5 (Ω) 〈6 (W) or more〉
Duty Cycle	8 (%) or less
Max ON Time	50 (msec)
Coil Saturation Temperature Rise $\Delta\theta_s$ (at 20 °C)	$\Delta\theta_s = 17 \times W \ (^{\circ}C)$ $K = 17 \ (^{\circ}C/watt)$
Temperature Rise Time Constant $ au$	4.5 (minutes)
Heat-Resistant Class	Class E (120℃)
Insulation Resistance	500 V DC MEGA, 100 MΩ or more
Dielectric Strength	1000 V AC, 50/60 Hz, 1 minute
Mass	45 (g)
Non-Excited Holding Force	3 (N) or more
Response Speed *1	9 (msec)

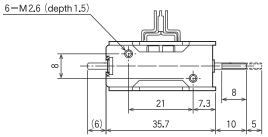


#### **◆** Attractive Force Data



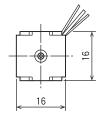
#### **◆** External Dimensions (mm)





#### **Terminal Specifications**

Lead Wire Length (mm): 200 AWG Size: 26



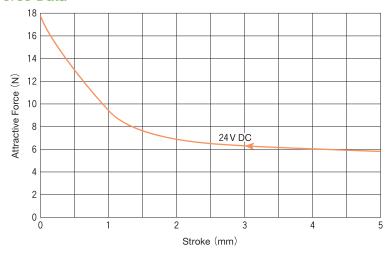
<sup>\*1:</sup> measurement conditions: measured by Takano Co. in a standard testing environment, with no load, shaft in a horizontal position, applied voltage 24 V DC.

Working Voltage	24 (V DC)
DC Resistance	7.5 (Ω)
External Resistance	1 (Ω) 〈7 (W) or more〉
Duty Cycle	4 (%) or less
Max ON Time	100 (msec)
Coil Saturation Temperature Rise $\Delta\theta_s$ (at 20 °C)	$\Delta\theta_s = 17 \times W \ (^{\circ}C)$ $K = 17 \ (^{\circ}C/watt)$
Temperature Rise Time Constant $ au$	5 (minutes)
Heat-Resistant Class	Class E (120℃)
Insulation Resistance	500 V DC MEGA, 100 MΩ or more
Dielectric Strength	1000 V AC, 50/60 Hz, 1 minute
Mass	65 (g)
Non-Excited Holding Force	5 (N) or more
Response Speed *1	7 (msec)

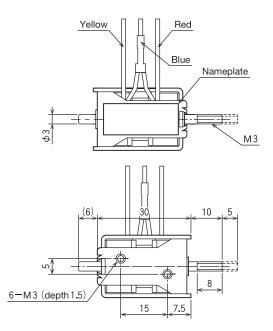


<sup>\*1:</sup> measurement conditions: measured by Takano Co. in a standard testing environment, with no load, shaft in a horizontal position, applied voltage 24 V DC.

#### ◆Attractive Force Data

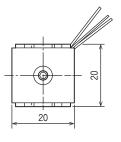


#### **◆ External Dimensions** (mm)



#### **Terminal Specifications**

Lead Wire Length (mm): 210 AWG Size: 26

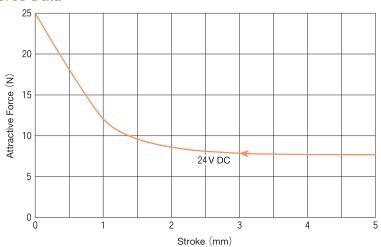


Working Voltage	24 (V DC)
DC Resistance	20 (Ω)
External Resistance	10 (Ω) 〈4 (W) or more〉
Duty Cycle	20 (%) or less
Max ON Time	40 (msec)
Coil Saturation Temperature Rise $\Delta\theta_s$ (at 20 °C)	$\Delta\theta_s = 12 \times W \ (^{\circ}C)$ $K = 12 \ (^{\circ}C/watt)$
Temperature Rise Time Constant $ au$	9 (minutes)
Heat-Resistant Class	Class E (120℃)
Insulation Resistance	500 V DC MEGA, 100 MΩ or more
Dielectric Strength	1000 V AC, 50/60 Hz, 1 minute
Mass	140 (g)
Non-Excited Holding Force	15 (N) or more
Response Speed *1	15 (msec)

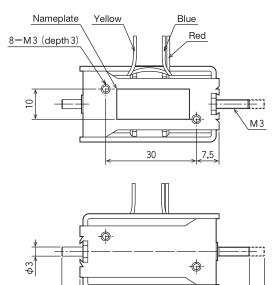


<sup>★1:</sup> measurement conditions: measured by Takano Co. in a standard testing environment, with no load, shaft in a horizontal position, applied voltage 24 V DC.

#### **◆** Attractive Force Data

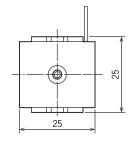


#### ◆External Dimensions (mm)



45

### **Terminal Specifications** Lead Wire Length (mm): 210 AWG Size: 26



10

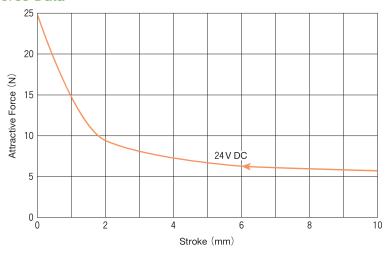
TSB-1010

Working Voltage	24 (V DC)
DC Resistance	20 (Ω)
External Resistance	15 (Ω) 〈4 (W) or more〉
Duty Cycle	20 (%) or less
Max ON Time	40 (msec)
Coil Saturation Temperature Rise $\Delta\theta_s$ (at 20 °C)	$\Delta\theta_s = 12 \times W \ (^{\circ}C)$ $K = 12 \ (^{\circ}C/watt)$
Temperature Rise Time Constant $ au$	9 (minutes)
Heat-Resistant Class	Class E (120℃)
Insulation Resistance	500 V DC MEGA, 100 MΩ or more
Dielectric Strength	1000 V AC, 50/60 Hz, 1 minute
Mass	120 (g)
Non-Excited Holding Force	10 (N) or more
Response Speed *1	20 (msec)

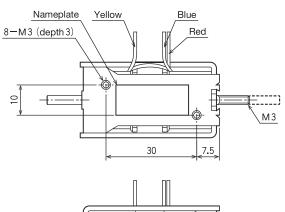


<sup>\*1:</sup> measurement conditions: measured by Takano Co. in a standard testing environment, with no load, shaft in a horizontal position, applied voltage 24 V DC.

#### **◆** Attractive Force Data



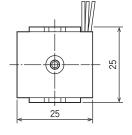
#### **◆ External Dimensions** (mm)



## • 45 10 10 11

#### **Terminal Specifications**

Lead Wire Length (mm): 210 AWG Size: 26



# TSB-LS (Low-Noise Model)

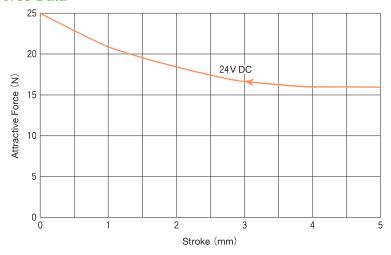
#### ◆ Main Specifications

	1
Working Voltage	24 (V DC)
DC Resistance	5 (Ω)
External Resistance	1 (Ω) 〈12 (W) or more〉
Duty Cycle	5 (%) or less
Max ON Time	40 (msec)
Coil Saturation Tempera-	$\Delta\theta_s = 12 \times W (^{\circ}C)$
ture Rise Δθ <sub>s</sub> (at 20 °C)	K≒12 (°C/watt)
Temperature Rise Time	9 (minutes)
Constant τ	5 (minutes)
Heat-Resistant Class	Class E (120℃)
Insulation Resistance	500 V DC MEGA, 100 MΩ or more
Dielectric Strength	1000 V AC, 50/60 Hz, 1 minute
Mass	120 (g)
Non-Excited Holding Force	2 (N) or more
Response Speed *1	6 (msec)

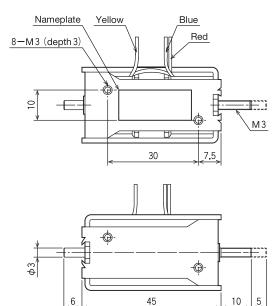


<sup>\*1:</sup> measurement conditions: measured by Takano Co. in a standard testing environment, with no load, shaft in a horizontal position, applied voltage 24 V DC.

#### ◆Attractive Force Data

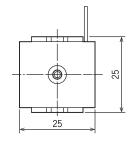


#### **◆External Dimensions** (mm)



# Lead Wire Length (mm): 210 AWG Size: 26

**Terminal Specifications** 



# **LATCHING SOLENOID VALVES**

## **Power-Saving**

Power is supplied only when operating.

#### **Low Heat**

 Keeps the valve open and closed after it moves.

## **High Chemical Resistance**

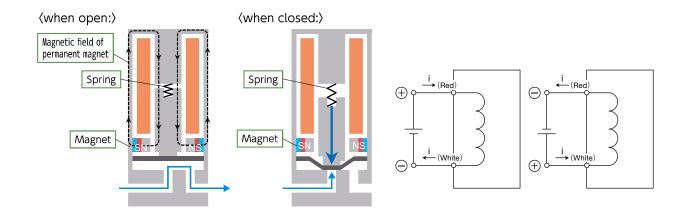
- Body: SUS
- Diaphragm: FKM

#### **FEATURES**

## **Product Characteristics**

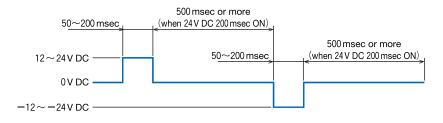
Open: While the valve is open, the magnetic field of the permanent magnet rotates in the direction of the dotted line in the figure below to maintain its closed state.

Close: While the valve is closed, a spring inside the operating iron core maintains the deviation state.



## **Operation**

Red lead wire (Voltage +), White lead wire (Voltage 0 V DC): (valve open) Red lead wire (Voltage 0 V DC), White lead wire (Voltage +): (valve open)



Valve Type	Diaphragm Type Direct Operated Poppet		
Fluid	Gas: Air, Nitrogen, Oxygen, Argon, etc.*1		
	Liquid: Water, Pure Water, Chemicals *1		
Operating Pressure Range	0~500 (kPa)		
Connection Bore Diameter	M 5		
Proof Pressure	1.0 (MPa)		
Fluid Temperature	Gas: 0∼50 (°C)		
	Liquid: 5∼50 (°C)		
Ambient Temperature	0∼50 (°C)		
Ambient Humidity	30~90 (%)		
Flow Factor Cv	0.06		
Orifice Diameter	1.1 (mm)		
Mass	106 (g)		
Life Cycle/Durability	100,000 (cycles)		
Material of Contact Area	Body: SUS		
	Diaphragm: FKM		
Material of Gas Contact Area	SUS 316, Electromagnetic SUS, FKM		
Response Speed *2	30 (msec) or less		
Electrical Specifications			
Working Voltage	12~24 (V DC)		
DC Resistance	25 (Ω)		
Heat-Resistant Class	Class E (120°C)		



- \* 1: The fluid does not corrode materials in the contact area.
- ★ 2: Measurement conditions Standard test environment: Vertical drive state, 12 (V DC) Application.

#### **♦ External Dimensions** (mm)

